

D.O.

# ING. DR. DANIEL OPOKU

PROFESSIONAL ELECTRICAL AND ELECTRONIC ENGINEER  
LECTURER AND RESEARCHER  
KWAME NKRUMAH UNIVERSITY OF SCIENCE AND TECHNOLOGY

## OBJECTIVE

Seeking a research consultancy opportunity where I can apply my knowledge and experience in instrumentation, control and automation to improve the living conditions of humanity.

## PROFESSIONAL SUMMARY

Professional Electrical and Electronic Engineer with many years of research and development experience in intelligent systems, instrumentation, controls and automation and about 3 years of experience in consultancy.

## EXPERIENCE

### LEAD CONSULTANT • COMPTON GHANA INTEGRATED LTD • JULY 2018 - DATE

- **Risk Assessment and Security Audit for Volta River Authority (VRA):** Partook in proposal writing, pre-contract engagements, led a team of 6 consultants to conduct Risk Assessment and Security Audit for all the major VRA Installations, conducted oral presentations, made recommendations, wrote technical report.
- **Risk Assessment and Security Audit for ECG Installations in the Greater Accra Region:** Led a team of 6 consultants to conduct Risk Assessment and Security Audit for all the Bulk Supply Points, Substations/Switchyards and other facilities of ECG in the Greater Accra Region, conducted oral presentations, made recommendations, wrote technical report.

### LECTURER AND RESEARCHER • KWAME NKRUMAH UNIVERSITY OF SCIENCE AND TECHNOLOGY • NOVEMBER 2016 - DATE

- Teaching and Researching in the field of Instrumentations, Controls, Automation and Intelligent Systems.
- Marketing and Outreach Officer for KNUST Engineering Education Project (KEEP), and Africa Center of Excellence (ACE) Impact.
- Mentoring of Students and Supervising of Student Projects
- College of Engineering Innovation Team Member
- Design/Drawings for Instrumentation, SCADA systems
- Electrical Motors and Pump Circuits Design, Drawing and Specifications

### NAVIGATION SYSTEMS ENGINEER/TEST ENGINEER • MERCURY DATA SYSTEMS INC, LEXINGTON KENTUCKY, USA • SEPTEMBER 2014 – AUGUST 2016

- Design of Laboratory Testing Procedures for Navigation Sensors
- Research and Development of Sensor Noise Models for Navigation Sensors
- Simulation and Prototyping of Virtual Inertia Measurement Unit (vIMU)

### POSTGRADUATE RESEARCH ASSOCIATE • ACIT CENTER, NORTH CAROLINA A & T STATE UNIVERSITY, GREENSBORO, NC, USA • SEPTEMBER 2013 – AUGUST 2014

- Concept Development for a Perception Inference Engine
- Server Administration for (ACIT) Center
- Proposal Writing and Technical Reporting



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## SKILLS

Artificial Intelligence, Power Systems Analysis with PSS@E, Automation Systems (Instrumentation, Controls, PLC, SCADA, etc), Design and Simulation using MATLAB/SIMULINK/SIMSCAPE, Native iOS Developer

## EDUCATION

### PHD IN ELECTRICAL ENGINEERING • JULY 2013 • NORTH CAROLINA A & T STATE UNIVERSITY

- **Dissertation Topic:** A Novel Approach to Intelligent Navigation of a Mobile Robot in a Dynamic and Cluttered Indoor Environment
- GPA of 4.0/4.0
- Among Top 10 Graduating Students.

### BSC IN ELECTRICAL AND ELECTRONIC ENGINEERING • JULY 2007 • KWAME NKRUMAH UNIVERSITY OF SCIENCE AND TECHNOLOGY

- First Class Honors with CWA of 76.38%
- Top 10 Graduating Students in Electrical and Electronic Engineering Department

## RESEARCH AREAS

- **Modern Controls Theories and Applications**
- **Unmanned Aerial Vehicles**
- **Electric Vehicles**
- **Artificial Intelligence and IoT**
- **Sensors and Instrumentations**
- **Industrial Control and Automation**

## CURRENT COURSES TAUGHT

### UNDERGRADUATES

- **Electromechanical Energy Conversion and Transformers**
- **Digital Systems**
- **Electrical Measurement and Instrumentations**
- **Classical Control Systems**
- **Digital Control Systems**



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### POSTGRADUATES

- **Computational Methods and Tools**

### VOLUNTEER EXPERIENCE OR LEADERSHIP

- **Committee Chairman:** Unity Hall Fellows Welfare Committee, FECE Course Mapping Committee, College of Engineering Online Learning Facilitation Committee.
- **Committee Member:** Tracer Committee, CoE Innovation Committee, KNUST Online Training Core Team, etc.
- **Positions:** Department Industrial Liaison Officer, College Industrial Presentations Coordinator, Examinations Officer, Department Field Trip Coordinator, etc.

### RESEARCH PUBLICATIONS

- [1] **Opoku, D.**, Benjamin Kommey (2020), FPGA-Based Intelligent Traffic Controller with Remote Operation Mode, International Journal of Innovative Technology and Interdisciplinary Sciences, Volume 3, Issue 4, DOI: <https://doi.org/10.15157/IJITIS.2020.3.3.490-500>
- [2] Adom-Bamfi, G., **Daniel Opoku**, Benjamin Kommey (2020), Welcoming the Semiconductor Industry in Ghana: Challenges and Recommendations – A Case Study, Journal of Engineering Studies and Research, Volume 26, No. 4, pp 27-33,
- [3] Kommey B., S. D. Kotey, **D. Opoku (2019)**, Patient Medical Emergency Alert System, International Journal of Applied Information Systems (IJ AIS), Volume 12, ISSN: 2249-0868.
- [4] Kommey B., Seth D. Kotey, **D. Opoku (2019)**, Biometric Course Attendance Monitor for KNUST, International Journal of Industrial Research and Applied Engineering (JIRAE), Volume 3, pp. 86-91, e-ISSN 2407-7259.
- [5] Kommey B., Seth D. Kotey, **D. Opoku (2020)**, Ultrasonic Sensor-Based Automated Water Dam Shutter, Journal of Information Technology and Computer Engineering (JITCE), Volume 4, pp 1-4.
- [6] **Opoku, D.**, A. Homaifar, and E. Tunstel (2013). The A-r-Star (Ar\*) Pathfinder. International Journal of Computer Applications; vol. (67), pp. 0975-8887.



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- [7] **Opoku, D.**, A. Homaifar, and E. Tunstel (2013). Towards the Incremental A-r-Star, Conference paper, World Conference on Soft Computing, Volume (312), pp. 191-202
- [8] **Opoku, D.**, A. Homaifar. (2010). Non-Classical Multi-Sensor Data Fusion Techniques. Conference proceedings, IEEE Aerospace Conference, ISBN 978-1-4244-3888-4.
- [9] **Enyinna N.**, A. Karimoddini, **D. Opoku**, A. Homaifar, S. Arnold. (2015). Developing an interval type-2 tsk fuzzy logic controller; Proc. of Fuzzy Information Processing Society (NAFIPS)/World Conference on Soft Computing (WConSC), 2015. Pp.1-6
- [10] **Opoku, D.**, A. Homaifar, and E. Tunstel (2014), RFID-augmentation for improving long-term pose accuracy of an indoor navigating robot, 2014 IEEE International Conference on Systems, Man and Cybernetics (SMC). Pp. 796-801
- [11] **Opoku, D.**, A. Homaifar, and E. Tunstel (2016), Path Planning for Planetary Surface Exploration Using Incremental A-r-Star Pathfinder,” Proc. 2016 NSBE Aerospace Systems Conference, Arlington, VA, Aug. 2016, pp. 144-148.



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